Stability for anisotropic curvature functionals

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Happy birthday Michael and Guofang



Scan me for the slides!

**Isoperimetric problem**: Determine properties of area minimising surface, given volume constraint.

Round spheres in  $\mathbb{R}^{n+1}$  are unique closed minimisers of

$$\mathcal{R}(\Omega) = rac{\mathsf{Area}^{rac{n+1}{n}}(\partial\Omega)}{\mathrm{Volume}(\Omega)}$$

Standard variational methods:

Minimisers of R have constant mean curvature

$$H=\operatorname{tr}(A)=\sum_{i=1}^n\kappa_i$$

 $(\kappa_i)$  are eigenvalues of the Weingarten map A, principal curvatures.

#### Alexandrov's theorem

Is a closed embedded constant mean curvature (CMC) hypersurface of  $\mathbb{R}^{n+1}$  necessarily a sphere?

Answer: **YES!** (Alexandrov<sup>1</sup>)

- Proof: Reflection across moving planes and the maximum principle.
- We are going to see another elegant proof today.

Relaxed CMC condition: Suppose for some  $\delta > 0$ , on a hypersurface M

$$n-\delta \leq H \leq n+\delta.$$

Can we conclude

$$dist(M, S) \leq C\epsilon$$

for the unit sphere S, a constant C and where

$$\lim_{\delta \to 0} \epsilon(\delta) = 0 ?$$

<sup>&</sup>lt;sup>1</sup>A characteristic property of spheres, Ann. Mat. Pura Appl. **58** (1962), no. 4, 303–315.

#### Theorem (Giulio Ciraolo and Luigi Vezzoni)

A sharp quantitative version of Alexandrov's theorem via the method of moving planes, J. Eur. Math. Soc. **20** (2018), no. 2, 261–299.

Let  $\Omega$  be a smooth domain with connected boundary, then  $\partial\Omega$  lies within an annulus of thickness  $C \operatorname{osc}(H)$ . C depends on  $|\partial\Omega|$  and a lower bound for interior and exterior balls.

Generalization to spaceforms and other curvature functions

$$F = F(\kappa_i)$$

was given by Ciraolo/Roncoroni/Vezzoni.<sup>2</sup>

<sup>2</sup> Quantitative stability for hypersurfaces with almost constant curvature in space forms, Ann. Mat. Pura Appl. **200** (2021), no. 5, 2043–2083.

#### Theorem (Rolando Magnanini and Giorgio Poggesi)

On the stability for Alexandrov's soap bubble theorem, J. Anal. Math. **139** (2019), no. 1, 179–205.

Let  $\Omega$  be a smooth domain with connected boundary, then  $\partial\Omega$  lies within an annulus of thickness at most  $C \|H - H_0\|_{L^1(\partial\Omega)}^{\tau_n}$ , where

$$H_0 = \frac{n}{n+1} \frac{|\partial \Omega|}{|\Omega|},$$

 $\tau_n$  is a dimensional constant and C depends on few geometric quantities, such as interior and exterior ball conditions.

#### Ambient anisotropic geometry

- Let  ${\cal W}$  (aka Wulff shape) be the smooth boundary of a convex body  ${\cal W}_0$  containing the origin.
  - Minkowski norm

$$F^0(x) = \inf\{s > 0 \colon x \in s\mathcal{W}_0\}$$

• Then  $W = \{F^0 = 1\}.$ 

•  $q(x) = \frac{1}{2}(F^0(x))^2$  is smooth and strictly convex, hence

$$\bar{g}(x) := D^2 q(x)$$

is a metric on  $\mathbb{R}^{n+1} \setminus \{0\}$ .

• Let  $F(z) = \sup_{x \in \mathcal{W}} \langle x, z \rangle$  be the support function of  $\mathcal{W}$ ,

- $\Phi = (\operatorname{grad} F)_{|\mathbb{S}^n} \colon \mathbb{S}^n \to \mathcal{W}$  is an embedding of the Wulff shape.
- $\Phi$  is the inverse of the Gauss map of  $\mathcal{W}$ .

#### Induced anisotropic geometry

- Let  $x: M^n \to \mathbb{R}^{n+1}$  embedding with M closed manifold,  $\tilde{\nu}: M \to \mathbb{S}^n$  its normal vector field aka Gauss map.
  - Anisotropic normal ν = Φ ∘ ν̃ = "position ν(x) on the Wulff shape, at which the normal of the Wulff shape equals ν̃(x)"
- Tangent space coincidence:  $T_x M = T_{\tilde{\nu}(x)} \mathbb{S}^n = T_{\nu(x)} \mathcal{W}.$ 
  - Homogeneity of  $F^0$  implies for all tangent vectors  $V \in T_x M$ ,

$$ar{g}_
u(
u,
u)=1,\quad g_
u(
u,
V)=0$$

Induced anisotropic metric and second fundamental form:

$$g_{ij}(x) = \bar{g}_{\nu(x)}(\partial_i x, \partial_j x), \quad h_{ij} = \bar{g}_{\nu(x)}(\partial_i \nu, \partial_j x).$$

• Anisotropic mean curvature  $H = g^{ij}h_{ij} \equiv tr(A)$ .

Anisotropic volume element dµ = F(ṽ)d vol<sub>n</sub> (≠ volume element induced from g).

#### Level sets

• For a function f on  $\mathbb{R}^{n+1}$ , define the *F*-gradient by

$$\nabla_F^{\sharp} f = F(D^{\sharp} f) D^{\sharp} F(D^{\sharp} f).$$

• On a regular level set M of f this coincides with the definition

$$ar{g}_{
u(x)}(
abla^{\sharp}_{F}f,V)=Df(x)V\quad orall V\in T_{x}M.$$

• Define the F-Hessian endomorphism by

$$\nabla_F^2 f = D^2(\frac{1}{2}F^2)(D^{\sharp}f) \circ D^2 f$$

• On a regular level set M of f this coincides with

$$\nabla_F^2 f = \bar{g}_{\nu(x)}^{-1} \circ D^2 f$$

• Operator degenerates where Df = 0.

### Anisotropic level-set stability

#### Theorem (with Xuwen Zhang)

Stability of the Wulff shape with respect to anisotropic curvature functionals, (2023).

Let  $n \ge 2$ ,  $M \subset \mathbb{R}^{n+1}$  closed hypersurface, F an elliptic integrand,  $\mu(M) = 1$ . Let  $\mathcal{U}$  be one-sided neighbourhood of M, given by level sets of  $f \in C^2(\overline{\mathcal{U}})$ ,

$$\bar{\mathcal{U}} = \bigcup_{0 \le t \le \max|f|} M_t, \quad M_t = \{|f| = t\},$$

with  $f_{|M}=0$  and  $df_{|\bar{\mathcal{U}}}>0.$  Let p>n and  $\max_{0\leq t\leq \max|f|}\|A\|_{p,M_t}\leq C_0.$  Then

$$\mathsf{dist}(M,\mathcal{W}) \leq \frac{C(n,p,F,C_0)}{\min(\max|f|,\min|df|)^{\frac{p}{p+1}}} \left(\int_{\mathcal{U}} |\mathring{\nabla}_F^2 f|^p\right)^{\frac{1}{p+1}}$$

for the Wulff shape corresponding to F, provided the RHS is small.

If h is the anisotropic  $2^{nd}$  fundamental form of any regular level set of f, then

$$abla^2 f_{|M} = F(D^{\sharp}f)h.$$

Hence

$$F^2(D^{\sharp}f)|\mathring{A}|^2 \leq |\mathring{\nabla}_F^2 f|^2,$$

where  $\mathring{A}$  is the tracefree part of the anisotropic second fundamental form,

$$|\mathring{A}|^2 = c_n \sum_{i < j} (\kappa_i - \kappa_j)^2.$$

Hence  $\mathring{A}$  can be controlled by  $\mathring{\nabla}_F^2 f$ .

Classical result from (isotropic) hypersurface theory, due to Darboux:

$$\AA=0 \quad \Rightarrow \quad M={\sf Sphere}.$$

A similar result holds in the anisotropic world<sup>3</sup>

Stability versions in the isotropic case are plentyfull and due to De Lellis/Müller, Topping, Grosjean.

In the anisotropic world there is a recent one...

<sup>&</sup>lt;sup>3</sup>Yijun He and Haizhong Li: Integral formula of Minkowski type and new characterization of the Wulff shape, Acta Math. Sin. **24** (2008), no. 4, 697–704.

### Some words about the proof

#### Theorem (Antonio De Rosa, Stefano Gioffré)

Absence of bubbling phenomena for non-convex anisotropic nearly umbilical and quasi-Einstein hypersurfaces, J. Reine Angew. Math. **780** (2021), 1–40.

Let  $M \subset \mathbb{R}^{n+1}$  be a closed hypersurface,  $\mathcal{W}$  a Wulff shape, p > n and

 $|M| = |\mathcal{W}|, \quad ||A||_{L^p(M)} \leq c_0.$ 

Then there exist  $C = C(n, p, F, c_0) > 0$ , such that: if

$$\|\mathring{A}\|_{L^p(M)} \leq \frac{1}{C},$$

then there exists  $c \in \mathbb{R}^{n+1}$  and a parametrization  $\psi \colon W \to M$ , such that

$$\|\psi-\mathsf{id}-c\|_{W^{2,p}(\mathcal{W})}\leq C\|\mathring{A}\|_{L^p(M)}.$$

• Stability of the domain in the Heintze-Karcher inequality. In the Euclidean space  $\mathbb{R}^{n+1}$ , for every domain  $\Omega$  with mean-convex  $\partial \Omega$ :

$$\int_{\partial\Omega}\frac{n}{H}\geq (n+1)\operatorname{vol}(\Omega)$$

with equality precisely when  $\Omega$  is a ball.

The same holds in the anisotropic setting, if we integrate w.r.t. the anisotropic area measure. Theorem (with Xuwen Zhang, Stability in the anisotropic Heintze-Karcher)

Let  $n \geq 2$ ,  $\alpha > 0$  and F be an elliptic integrand on  $\mathbb{R}^{n+1}$ . Let  $\Omega \subset \mathbb{R}^{n+1}$  be a bounded domain with connected F-mean convex  $C^{2,\alpha}$ -boundary that satisfies a uniform interior Wulff sphere condition with radius r. Then there exists a positive constant C depending only on  $n, \alpha, F, r, \mu(\partial \Omega)$  and  $|\partial \Omega|_{2,\alpha}$ , such that

$${\sf dist}(\partial\Omega,\mathcal{W})\leq C\left(\int_{\partial\Omega}rac{1}{H}\,d\mu-rac{n+1}{n}|\Omega|
ight)^{rac{1}{n+2}}$$

for some Wulff sphere  $W \subset \mathbb{R}^{n+1}$ , provided the RHS is sufficiently small.

#### Proof of Heintze-Karcher stability

• The key for stability is the following estimate

$$\int_{\Omega} |\mathring{\nabla}_F^2 f|^2 \, dx \leq \left(\frac{n}{n+1}\right)^2 \int_{\partial \Omega} \frac{1}{H} \, d\mu - \frac{n+1}{n} |\Omega|,$$

where

$$\operatorname{div}(D^{\sharp}(\frac{1}{2}F^{2})(D^{\sharp}f)) =: \Delta_{F}f = 1 \quad \text{in } \Omega$$
$$f = 0 \quad \text{on } \partial\Omega.$$

- Follows from divergence theorem type argument and Hölder's inequality.
- *f* shall serve as the foliation function in a neighbourhood of  $\partial \Omega$ .
- For this we need a lower gradient bound of f on  $\partial \Omega$ .

## Proof of Heintze-Karcher stability

#### Lemma (Gradient bound on $\partial \Omega$ )

Let  $\Omega \subset \mathbb{R}^{n+1}$  be a bounded domain with  $C^2$ -boundary that satisfies the uniform interior Wulff sphere condition with radius r and let  $f \in C^{1,\beta}(\overline{\Omega}) \cap W^{2,2}(\Omega)$  for some  $\beta \in (0,1)$  be a solution of

$$\operatorname{div}(D^{\sharp}(rac{1}{2}F^2)(D^{\sharp}f)) = 1 \quad \textit{in } \Omega \ f = 0 \quad \textit{on } \partial \Omega$$

then

$$|D^{\sharp}f| \geq C(n,F)r$$
 on  $\partial\Omega$ .

- From here, higher regularity in a controlled neighbourhood of  $\partial\Omega$  follows from Schauder theory.
- The level set stability theorem completes the proof of the anisotropic Heintze-Karcher stability.

J. Scheuer

# Application II: Stability in the anisotropic soap bubble theorem

Theorem (with Xuwen Zhang, Stability in the anisotropic soap bubble theorem)

Let  $n \ge 2$ ,  $\alpha > 0$  and F be an elliptic integrand on  $\mathbb{R}^{n+1}$ . Let  $\Omega \subset \mathbb{R}^{n+1}$  be a bounded domain with connected boundary  $\partial \Omega \in C^{2,\alpha}$  that satisfies a uniform interior Wulff sphere condition with radius r. Then there exists a positive constant C depending only on  $n, \alpha, F, r, \mu(\partial \Omega)$ , such that

$$\mathsf{dist}(\partial\Omega,\mathcal{W}) \leq C \left\| \mathcal{H} - rac{n}{n+1} rac{\mu(\partial\Omega)}{|\Omega|} 
ight\|_{1,\partial\Omega}^{rac{1}{n+2}}$$

for some Wulff sphere  $W \subset \mathbb{R}^{n+1}$ , provided the RHS is sufficiently small.

## Integral approach

Key ingredient in the isotropic case (A. Ros): Use **Reilly's integral** identity.

For  $C^2$ -functions f on a domain  $\Omega \subset \mathbb{R}^{n+1}$ , with  $f_{|\partial\Omega} = \text{const}$ :

$$\int_{\Omega} (\Delta f)^2 - \int_{\Omega} |\nabla^2 f|^2 = \int_{\partial \Omega} H(\partial_{\nu} f)^2.$$

Cauchy-Schwarz-deficit:

$$|\mathring{\nabla}^2 f|^2 = |\nabla^2 f|^2 - \frac{1}{n+1} (\Delta f)^2,$$

Then

$$\int_{\Omega} |\mathring{\nabla}^2 f|^2 = \frac{n}{n+1} \int_{\Omega} (\Delta f)^2 - \int_{\partial \Omega} H(\partial_{\nu} f)^2.$$

Solve

$$\Delta f = 1$$
 in  $\Omega$   
 $f = 0$  on  $\partial \Omega$ .

## Integral approach

#### Then

$$\begin{split} \int_{\Omega} |\mathring{\nabla}^2 f|^2 &= \frac{n}{(n+1)\operatorname{vol}(\Omega)} \left( \int_{\Omega} \Delta f \right)^2 - \int_{\partial \Omega} H(\partial_{\nu} f)^2 \\ &= \frac{n}{(n+1)\operatorname{vol}(\Omega)} \left( \int_{\partial \Omega} \partial_{\nu} f \right)^2 - \int_{\partial \Omega} H(\partial_{\nu} f)^2 \\ &\leq \frac{n}{(n+1)} \frac{\operatorname{Area}(\partial \Omega)}{\operatorname{vol}(\Omega)} \int_{\partial \Omega} (\partial_{\nu} f)^2 - \int_{\partial \Omega} H(\partial_{\nu} f)^2 \\ &\equiv \int_{\partial \Omega} (H_0 - H)(\partial_{\nu} f)^2. \end{split}$$

## Application III: Serrin' problem

• Serrin's overdetermined problem asks which domains  $\Omega$  allow solutions to

$$\Delta u = 1 \quad \text{in } \Omega$$
$$u = 0 \quad \text{on } \partial \Omega$$
$$\nabla u | = c \quad \text{on } \partial \Omega.$$

The answer is: Only balls.

• The anisotropic version (yielding equality to the Wulff shape)

$$\operatorname{div}(D^{\sharp}(rac{1}{2}F^2)(D^{\sharp}f)) = 1 \quad ext{in } \Omega$$
  
 $f = 0 \quad ext{on } \partial \Omega$   
 $F(D^{\sharp}f) = c \quad ext{on } \partial \Omega$ 

is due to Cianchi/Salani.<sup>4</sup>

<sup>4</sup>Overdetermined anisotropic elliptic problems, Math. Ann. **345** (2009), no. 4, 859–881.

## Application III: Stability in the anisotropic Serrin problem

Theorem (with Xuwen Zhang, Stability in the anisotropic Serrin problem)

Let  $n \geq 2$ ,  $\alpha > 0$  and F be an elliptic integrand on  $\mathbb{R}^{n+1}$ . Let  $\Omega \subset \mathbb{R}^{n+1}$  be a bounded domain with connected boundary  $\partial \Omega \in C^{2,\alpha}$  that satisfies a uniform interior Wulff sphere condition with radius r. Then there exists a positive constant depending only on  $n, \alpha, F, r, \operatorname{diam}(\Omega), \mu(\partial \Omega)$  and  $|\partial \Omega|_{2,\alpha}$ , such that

$$\mathsf{dist}(\partial\Omega,\mathcal{W}) \leq C \left\| \mathsf{F}(D^{\sharp}f) - \frac{|\Omega|}{\mu(\partial\Omega)} \right\|_{1,\partial\Omega}^{\frac{1}{2(n+2)}}$$

for some Wulff sphere  $W \subset \mathbb{R}^{n+1}$ , provided the RHS is sufficiently small. Here

$$\operatorname{div}(D^{\sharp}(rac{1}{2}F^{2})(D^{\sharp}f)) = 1 \quad \textit{in } \Omega$$
  
 $f = 0 \quad \textit{on } \partial \Omega$ 

## Application III: Stability in the anisotropic Serrin problem

• The proof works via the use of a so-called P-function. In our setting,

$$P = rac{F^2(D^{\sharp}f)}{2} - rac{1}{n+1}f.$$

A computation gives

$$\operatorname{div}(\nabla_F^{\sharp} P) = |\mathring{\nabla}_F^2 f|^2.$$

• The next crucial ingredient is the Pohozaev-type identity

$$\int_{\Omega} \mathsf{P} = rac{1}{2(n+1)} \int_{\partial \Omega} \mathsf{F}^2(D^{\sharp}f) \langle x, ilde{
u} 
angle \,.$$

• Further computations lead to

$$\int_{\Omega} (-f) |\bar{\nabla}_F^2 f|^2 dx = \frac{1}{2} \int_M \left( F^2(D^{\sharp} f) - \frac{|\Omega|^2}{\mu(M)^2} \right) \left\langle \bar{\nabla}_F^{\sharp} f - \bar{\nabla}_F^{\sharp} \ell, \tilde{\nu} \right\rangle d\tilde{\mu},$$

where  $\ell(x) = (F^0(x))^2/(2(n+1))$ .

## Thank you!